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Award Number: DAMD17-00-1-0599

TITLE: High-Resolution Speckle-Free Ultrasound Imaging System-A
Potential Solution for Detecting Missed Breast Cancer

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REPORT DATE: October 2003

TYPE OF REPORT: Annual

PREPARED FOR: U.S. Army Medical Research and Materiel Command
Fort Detrick, Maryland 21702-5012

DISTRIBUTION STATEMENT: Approved for Public Release;
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20040226 048

REPORT DOCUMENTATION PAGE			Form Approved OMB No. 074-0188	
Public reporting burden for this collection of information is estimated to average 1 hour per response, including the time for reviewing instructions, searching existing data sources, gathering and maintaining the data needed, and completing and reviewing this collection of information. Send comments regarding this burden estimate or any other aspect of this collection of information, including suggestions for reducing this burden to Washington Headquarters Services, Directorate for Information Operations and Reports, 1215 Jefferson Davis Highway, Suite 1204, Arlington, VA 22202-4302, and to the Office of Management and Budget, Paperwork Reduction Project (0704-0188), Washington, DC 20503				
1. AGENCY USE ONLY (Leave blank)		2. REPORT DATE October 2003		3. REPORT TYPE AND DATES COVERED Annual (1 Oct 2002 - 30 Sep 2003)
4. TITLE AND SUBTITLE High-Resolution Speckle-Free Ultrasound Imaging System-A Potential Solution for Detecting Missed Breast Cancer			5. FUNDING NUMBERS DAMD17-00-1-0599	
6. AUTHOR(S) Matthew T. Freedman, M.D.				
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) Georgetown University Medical Center Washington, DC 20057 E-Mail: freedmmt@georgetown.edu			8. PERFORMING ORGANIZATION REPORT NUMBER	
9. SPONSORING / MONITORING AGENCY NAME(S) AND ADDRESS(ES) U.S. Army Medical Research and Materiel Command Fort Detrick, Maryland 21702-5012			10. SPONSORING / MONITORING AGENCY REPORT NUMBER	
11. SUPPLEMENTARY NOTES				
12a. DISTRIBUTION / AVAILABILITY STATEMENT Approved for Public Release; Distribution Unlimited				12b. DISTRIBUTION CODE
13. ABSTRACT (Maximum 200 Words) The Imperium Inc. transmission ultrasound system is a highly promising novel method for imaging the breast. In this pilot project, we are to work with Imperium to advise and help them modify their existing system for non-destructive testing into one suitable for breast imaging, perform a physics evaluation and perform a small clinical pilot feasibility trial. The initiation of this project was delayed by non-approval of the human use portion of the project. We have received US Army Human Use approval for study of tissue samples. During this past year, we provided technical advice to Imperium, and have performed physics tests and in imaging of pieces of animal tissue obtained in a supermarket. Imperium has improved the machine during this past year and we will be starting human tissue tests shortly. They have created a prototype of a dry system and have designed a potential system for clinical use that is yet to be constructed. We will describe some of these improvements in this annual report.				
14. SUBJECT TERMS Detection breast cancer, C-Scan ultrasound, CCD coupled Piezoelectric sensor, ultrasound lens				15. NUMBER OF PAGES 18
				16. PRICE CODE
17. SECURITY CLASSIFICATION OF REPORT Unclassified	18. SECURITY CLASSIFICATION OF THIS PAGE Unclassified	19. SECURITY CLASSIFICATION OF ABSTRACT Unclassified	20. LIMITATION OF ABSTRACT Unlimited	

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High-Resolution Speckle-Free Ultrasound Imaging System--A potential solution for detecting missed breast cancer

Introduction

The Imperium Inc. transmission ultrasound system is a highly promising novel method for imaging the breast. In this pilot project, we are to work with Imperium to advise and help them modify their existing system for non-destructive testing into one suitable for breast imaging, perform a physics evaluation of the system and perform a small clinical pilot feasibility trial. The initiation of this project was delayed by non-approval of the human use portion of the project. We now have approval for work in biopsy specimens and mastectomy specimens. I am not yet certain whether the system is ready for human trial and have not proceeded to in vivo studies. Imperium, Inc and Georgetown have been working to improve the technical capabilities of the machine and performing physics tests during the past year. We have requested a one-year no-cost extension for this project and this has been granted.

During this year, we have advised Imperium Inc., as they have worked to improve the system and broaden its applicability. Important modifications have been made in the design of the ultrasound source, lens design and improved dynamic range of the detector. The company has performed physics tests on the system as well.

Body

During the past year we have used only limited funds while awaiting Imperium's improvements to the machine. We have visited Imperium's R and D site and have worked with the system at Georgetown to learn how the controls operate and to suggest improvements that should be made. The original system used a water bath. This has been supplemented by a dry system in which fluid filled stand-off pads are used to make contact with the artificial tissue under evaluation. We accompanied the company when they had an informal conference with the FDA. This was done to start their learning process of the requirements for eventual FDA approval. Safety information was extensively discussed and there appear to be no safety concerns.

The following represents a combined presentation of work done by Imperium Ltd and Georgetown in testing the system prior to its use in human tissue specimens.

The initial system is a water bath system. A dry system has been constructed and is described later.

The Water Bath System:

To generate real-time images, ultrasound is introduced into the target under study with a large unfocused ultrasound plane wave. The resultant pressure wave strikes the target and is attenuated and scattered. An acoustic lens collects the energy and focuses it onto the ultrasound sensitive array. The array is made up of two components, a silicon detector/readout array and a piezoelectric material that is deposited onto the array through semiconductor processing (see Figure 1). The array is 1 cm on a side consisting of 128x128 pixel elements (16,384) with 85 μ m pixel spacing. The energy that strikes the piezoelectric material is converted to an analog voltage that is digitized and processed by low cost commercial video electronics.

Note that there is an ultrasound-receiving (piezoelectric) layer deposited onto the chip. A picture of the microarray is shown in Figure 2. The array is responsive over a wide range of ultrasound frequencies,

although most imaging is done between 1MHz and 10MHz. The use of a lens provides a simple, inexpensive alternative to complex beam forming often employed in ultrasound imaging. The user simply focuses by adjusting the lens while looking at the image on a monitor. Figures 3 and 4 show the overall system configuration and the laboratory setting in a water tank, respectively.

The system operates by pulsing a commercial off-the-shelf ultrasonic spike pulser in 5 MHz frequencies. This excites the large area unfocused ultrasound transducer (only used as a source) and sends an ultrasound plane wave through the water. This plane wave enters the target, scatters, exits the target and strikes the acoustic lens, which collects the scattered energy and focuses it onto the array. This operation repeats 30 times/second to generate real-time image. Standard video electronics and image processing are used to format the image for presentation to the user and perform real time image processing; either on a PC monitor or LCD.

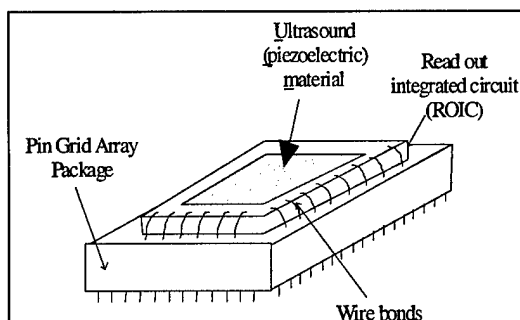


Figure 1. Schematic of array assembled array

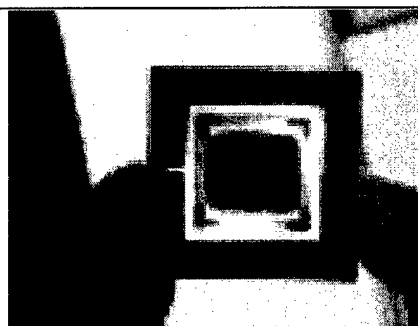


Figure 2. 128 x 128 assembled array

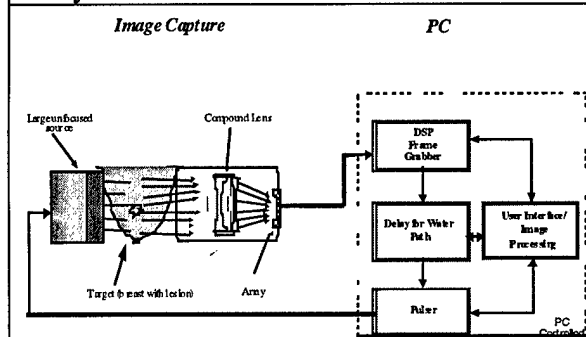


Figure 3. The prototype system configuration



Figure 4. Laboratory setting in a water tank

Contrast Resolution

The ability of the camera to resolve separate tissue layers is a function of its sensitivity to small changes in amplitude. We tested the camera's ability to resolve these small differences in detected signal level. The phantom used in this investigation was a custom-made Zerdine™-based phantom containing 3-mm and 5-mm spheres with small differences in attenuation from the surrounding background material. The phantom was manufactured by Computerized Imaging Reference Systems Inc. (CIRS, Norfolk, VA). The background material has an attenuation of 0.22 dB/cm/MHz that approximates the attenuation of fatty tissue [1, Table 4.6]. Two of the spheres were slightly less attenuating than the background and two of the spheres are slightly more attenuating than the background.

The ability to resolve amplitude differences is measured by calculating a Contrast to Noise Ratio (CNR), given by $CNR = (I_s - I_b) / \sqrt{(\sigma_s^2 + \sigma_b^2)/2}$, where the I_s and I_b are sphere and background mean intensities and σ_s and σ_b are the respective standard deviations. In these measurements, statistics for a block of image pixels inside and outside each sphere area were collected and analyzed. Transmission images were obtained with an Imperium I-100 camera, a two-element aspheric 50 mm diameter F/1 (Imperium 915 series), and a 5.4-MHz center frequency, 1.5 in. diameter pulsed transducer. Figure 5 shows the images taken of this phantom.

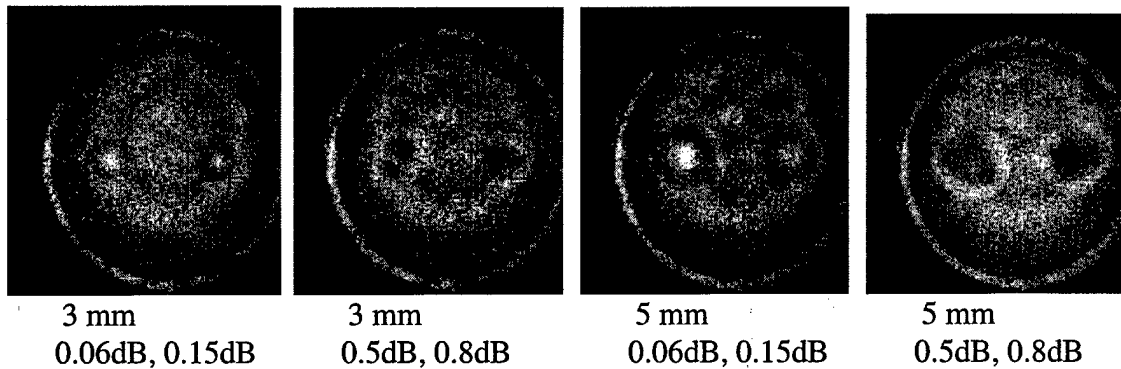


Figure 5 Transmission images of the CIRS contrast phantom.

The sphere diameters and their attenuations (dB/cm/MHz) are indicated in Figure 1. The overall circular field of view indicates the beam diameter. Note the edges around the spheres. The pronounced edges are caused by the refraction edge effect that tends to enhance object resolvability. This effect is known as phase contrast in gapped projection images [2]. We have described this phenomenon and its possible role in enhancing contrast mammography [3]

The results of the CNR calculations are shown in Table 1. Note that there are 256 grayscale levels to represent pixel intensities. This phantom was designed to mimic the breast with embedded cysts and solid masses. The spheres with attenuation less than the background material mimic cysts in this phantom. The spheres with attenuation greater than the background material mimic solid masses.

Table 1
Contrast Resolution

Sphere	Size (mm)	Differential Attenuation (dB)	Sphere Mean Intensity	Sphere Std. Dev.	Background Mean Intensity	Background Std. Dev.	Contrast	CNR
1	3	0.26	199	17	152	14	47	3.02
2	3	0.12	179	13	152	14	27	2.00
3	3	-0.45	117	11	154	16	-37	-2.69
4	3	-0.94	111	8	154	16	-43	-3.40
5	5	0.44	225	19	149	17	76	4.22
6	5	0.19	166	12	149	17	17	1.16

Sphere	Size (mm)	Differential Attenuation (dB)	Sphere Mean Intensity	Sphere Std. Dev.	Background Mean Intensity	Background Std. Dev.	Contrast	CNR
7	5	-0.75	138	12	157	17	-19	-1.29
8	5	-1.56	99	9	157	17	-58	-4.26

The contrast and CNR calculated in Table 1 must be viewed in the context of the amount of material contributed by the background and by the spheres. The attenuation of the background material is 0.22 dB/cm/MHz, the width of the phantom is 6 cm, and the center frequency of the transducer output is 5.4 MHz. The total attenuation through the phantom where there is no sphere is 7.13 dB. The differential attenuation column indicates the absolute difference between a phantom volume with no sphere and the phantom volume with spheres of different sizes and densities. The differential attenuation column in Table 1 is valid though the center of the sphere. Attenuation through off center sphere volumes will be closer to the background because there is less sphere material. It is notable that objects are resolvable with attenuation differences as small as 0.12 dB.

Dynamic Range

The dynamic range of the current system is set by the analog output of the camera and the 8-bit analog frame grabber used by the display system. The dynamic range of the next generation camera system is expected to be greater than 70 dB. The next generation camera will incorporate a 14-bit analog/digital converter (ADC) that will preserve the fidelity of the detector array in the accumulation of raw ultrasound data. We expect that the ultrasound data will be compressed to 8-10 bits for video display. Image compression techniques will be used to enhance the contrast resolution of the desired image area. With the use of a variable power output from the ultrasound transducer it is expected that the total dynamic range of the next generation camera will be well over 100 dB.

Twelve images were collected from a custom-fabricated dynamic range step phantom supplied by CIRS. These images are shown in Figure 6. A background pixel intensity of 57 was calculated by observing an area of the display in which there was a de-bonding of the piezo-electric material from the detector array. In this area there is no energy added to the pixel cells from ultrasound detection. Figure 7 shows a graph of pixel intensity versus the attenuation step. Each attenuation step is 2.7 dB.

The images were obtained with an Imperium I-100 camera, a two-element aspheric 50 mm diameter F/1 (Imperium 915 series), a 3.85 MHz center frequency, 1.5" diameter pulsed transducer. The peak sound pressure amplitude output from the transducer was 1.45 MPa.

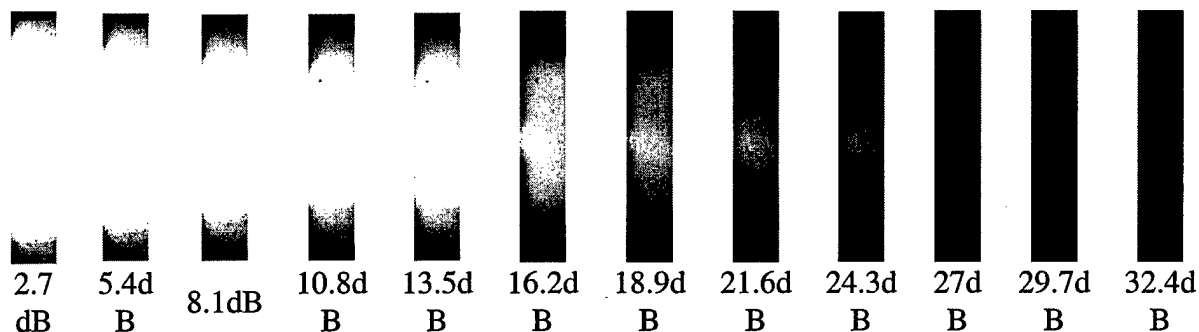


Figure 6. Twelve steps of the dynamic range phantom with associated attenuation @ 3.85 MHz.

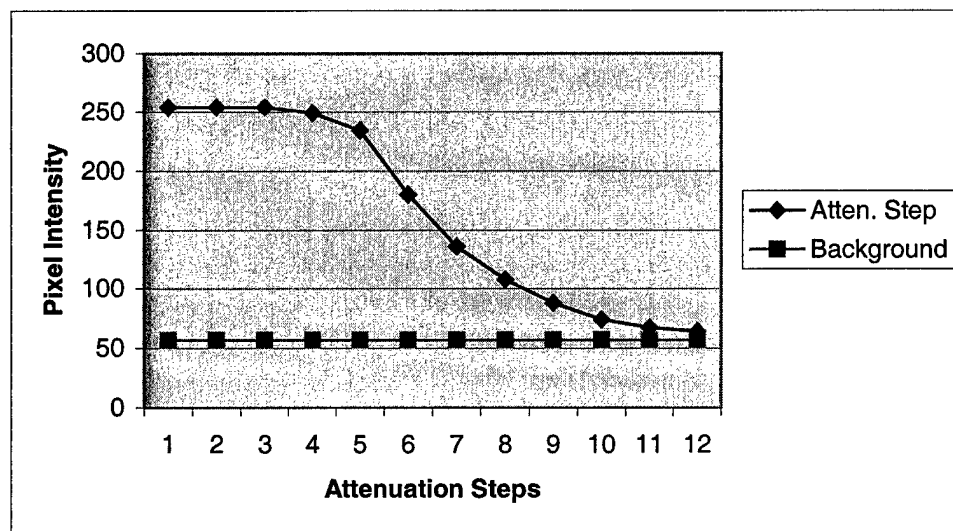


Figure 7 Dynamic Range of I100 Camera. Each attenuation step is 2.7 dB.

As a comment on the dynamic range performance, the camera was able to penetrate 32.4 dB of phantom material. The attenuation of the material at 0.70 dB/cm/MHz approximates that of the average for soft tissue ([1], pg. 51). The phantom is 17.1 cm or 6.84 in. thick at the 32.4 dB step, the current Imperium ultrasound camera should then be capable of penetrating more than 6 in. of soft tissue in its current configuration. Greater sensitivity is expected in the next generation of camera. In mammography, the normal compressed breast thickness varies from 3 to 8 cm depending on breast size and breast density. Thus the dynamic range results support the feasibility of using the Imperium camera for breast imaging (17 cm penetrating ability vs. 8 cm for maximum usual breast thickness).

Spatial Resolution

The purpose of this task is to investigate the ability of the camera to resolve separate objects in a field of view, a function of its spatial resolution. The custom-fabricated Zerdine™-based CIRS phantom used in this

investigation contains seven, 250 μm steel wires embedded in a fan shape. Transmission image data was obtained with an Imperium I-100 camera, a two-element aspheric 50 mm diameter F/1 (Imperium 915 series), and a 5.4-MHz center frequency, 1.5"-diameter pulsed transducer. Figure 8 shows an image taken of this phantom. Spatial resolution of the camera is determined by its ability to resolve the wires and the gaps between the wires.

The acoustic lenses designed by Imperium for its ultrasound cameras are diffraction limited. Eq. (1) describes the limit of resolution for the diffraction-limited lens used in this investigation.

$$D_L = 1.22\lambda F/D \quad \dots(1)$$

$$\lambda = 277 \mu\text{m} \text{ (5.4 MHz)}$$

$$D = \text{diameter of the aperture} = \text{diameter of the transducer} = 1.5 \text{ in.} = 3.75 \text{ cm}$$

$$F = \text{Focal Length} = 50 \text{ mm}$$

$$D_L = 451 \mu\text{m}$$

The above computation indicates that the resolution of the system used for this investigation should be about 500 μm . Images shown in Figure 8 and results of work by Ishisaka et al [2] indicate that the phenomenon of phase contrast acts to enhance the edges of objects and may significantly improve the resolution achievable over the limit of Eq. 1.

Quantitative results of the first spatial resolution investigation are shown in Figure 9. The intensity of the steel wires is shown as the lower pixel values and the gaps between the wires are shown as the higher values.

The center of the image in Figure 4 is 55 mm from the apex of the fan and the fan spreads at an angle of 4.77° . The distance between the outer two wires at the red line in Figure 4 is 9.17 mm. As can be seen, there is substantial blurring of the wires in the image. The aggregate width of seven, 250 μm wires is only 1.75 mm and so should account for only a small part of the width as seen in the image. The blurring is to be expected as the diameter of the wire is only half the spatial resolution predicted by Eq. 1. Observe that five of the six wire gaps are pronounced and one is obscured. This is due to an imperfection in the phantom. Two of the wires lay on top of each other.

The conclusion from this investigation is that we are limited by the operating frequency of the ultrasound camera. It is desirable that we should be able to resolve the 250 μm wires with no blurring. By doubling the frequency to 10 MHz it is predicted from Eq. 1 that we will be able to image the wires without blurring.

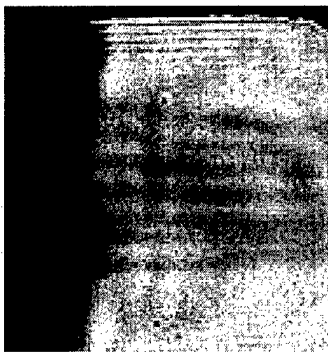


Figure 8 Wire Fan Phantom

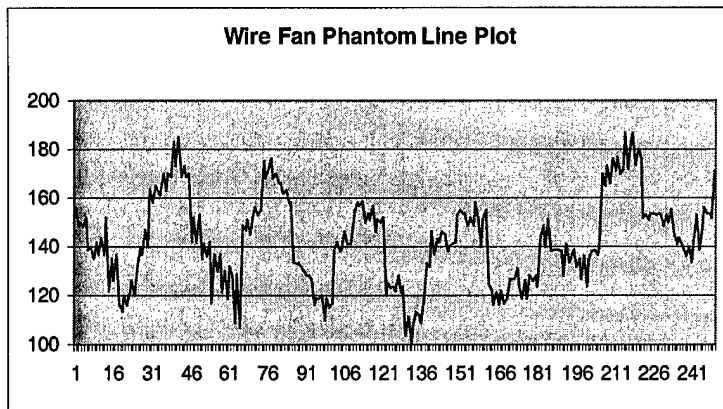


Figure 9 Fan Phantom Line Intensity Plot

A second spatial resolution test was conducted with a CIRS microcalcification phantom. It consisted of Zerdine™ material with imbedded calcium carbonate inclusions with diameters 150-160, 250-280, 320-355, 425-450, and 710-850 μm . Camera images are shown in Figure 10.



(a) 710-850 μm target group



(b) 425-450 μm target group



(c) 300-355 μm target group

Figure 10

Figure 10a clearly shows 700 μm targets. 700 μm is greater than the calculated resolution and thus it is expected that the targets will be easily seen. Figure 10b shows the presence of 450 μm targets but the resolvability of the targets is strained. A single target is clearly seen and other targets are less clearly seen. Unfortunately, most of the targets in this phantom are placed on the lip of an Acrylic dish that holds the targets in place. This is unfortunate because there are refraction effects at the boundaries of this lip that make the targets hard to see. Figure 10c shows the presence of 300 μm targets. The targets in this phantom are blurred as would be expected when the targets are smaller than the resolution limit.

We also evaluated the intensities of the calcification flecks in this phantom. The results are shown in figure 11.

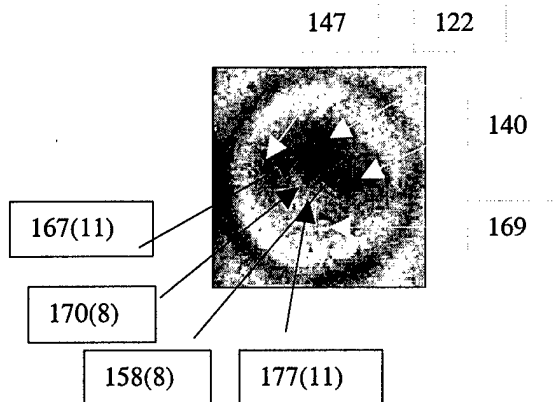


Figure 11: CIRS phantom with calcifications ROIs and their intensities and CNRs measures for the smallest clustered calcifications. (A) Four intensity measures for the calcifications upper-right corners and the intensity (noise level) measures at selected background areas

Potential methods to improve resolution

From Eq. 1 it can be seen that resolution can be improved by increasing the frequency, decreasing the focal length, or increasing the diameter of the lens. Decreasing the focal length of the system used in this investigation is impractical. With a lens diameter of 50 mm and a focal length of 50 mm, the current design utilizes a F1 lens. Implementing a smaller focal length would be difficult. Increasing the lens size is possible but there are mechanical limits due to the extended water path. Imperium is currently working on a 3-in. lens design and is investigating the feasibility of a 5 in. lens. One problem with increasing the lens diameter is that the focal length must necessarily increase.

The most practical way to improve resolution is to increase the ultrasound frequency. Eq. 1 is linear, so doubling the frequency to 10 MHz would result in a halving of the resolution to 244 μm . Imperium proposes that increasing the frequency to 13 MHz poses no significant technical problem. The issue in increasing the ultrasound frequency is the increase in attenuation. The tradeoff between increased attenuation and improved resolution will be evaluated in the context of imaging breast tissue. Most conventional B-scan ultrasound systems operate at 12-13 MHz for imaging the human breast so the use of frequencies higher than 10 MHz is likely for the proposed system.

Zoom Lens Results

The ultrasound imaging system was set up and focused in a manner typically used for imaging with Imperium's ultrasound camera. The transducer was fixed in a position approximately 18 in. from the camera. The two lens elements are Imperium's two-element aspheric 2.75 in. diameter F/1 (Imperium 915 series) lens. Lens elements were moved relative to one another to achieve zoom. The change in image size and the lens positions were recorded. Image size was measured using the AcoustoVision Measurement™ tool (Imperium, Inc.).

Figure 12 shows the relationship of lens movement to image size. Note the monotonic change in image size versus lens change. This relationship is necessary to realize a practical zoom lens design

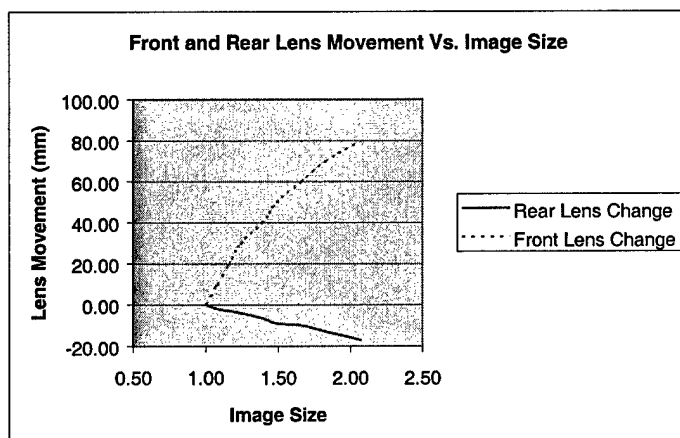


Figure 12 Lens Movement vs. Image Size

A 2:1 zoom was accomplished using a standard lens system by increasing the on-axis distance between the lenses. The front lens moved a distance of 80 mm and the rear lens moved 17 mm from the starting position. The images in Figure 13 show the reference image at the start and end points of the lens positions. Note the enlargement of the 1-in. marks on the ruler in Figure 13b.

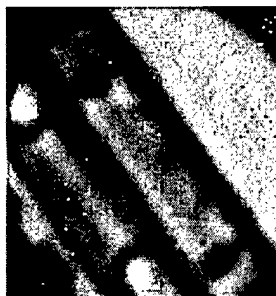


Figure 13a Image With no Magnification

Figure 13b Magnified Image

Large (3") Field Of View

Two large area-imaging lenses were designed using the Zemax Optical Design Program (Focus Software Inc, Tucson, AZ). Both lens systems are composed of a large diameter objective lens and two smaller focusing elements. The lenses were designed to be diffraction-limited across the surface of the lens. Based on the design in Figure 14, the blur spot size at any given point in the image plane should be no greater than $375\ \mu\text{m}$ for a lens with a three inch diameter, F/1 speed, and an ultrasound frequency of 5.0 MHz. Spot size estimates were performed for several points across the lens surface with the largest spot size occurring at the point farthest from the paraxial axis. The size of the plane wave to be focused and the size of the sensor array

determine the magnification of the lens design. In this case, the lens focused a 76.2 mm diameter wave front onto a 10.8 mm square sensor array yielding a magnification of 0.14.

$$m = h' / h = 10.8 \text{ mm} / 76.2 \text{ mm} = 0.14.$$

... (2)

m = magnification

h' = image height

h = object height

The first design consisted of two elements from the Imperium 915 lens with the addition of a third larger diameter objective lens. The working F-number of this design is 1.69 with an estimated off axis blur size of 375 μm . The Zemax Optical design program generated the ray tracing and spot size diagrams shown in Figure 14.

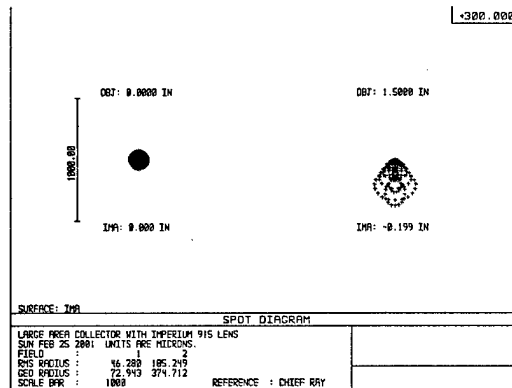
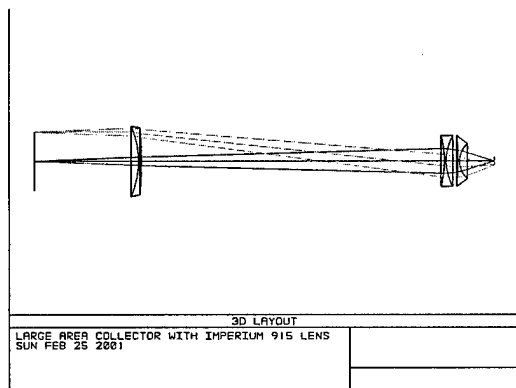


Figure 14a 3-in. Lens, Ray Tracing

Figure 14b 3-in. Lens with 375 micron spot size

A second, improved design is similar but consists of three newly designed lens elements. The working F-number of this design is 1.68 with an estimated off axis blur size of 150 μm . Ray tracing and spot size diagrams of the second design are shown in Figure 15.

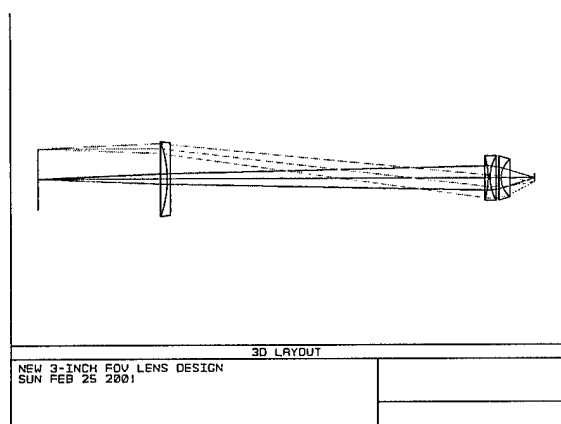


Figure 15a 3-in. Lens, Ray Tracing

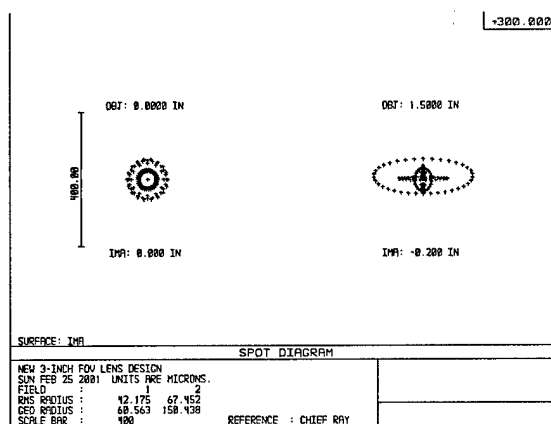


Figure 15b 3-in. Lens with 150 micron spot size

Dry System Implementation

A dry system (no water tank) is required as a practical approach to implementation of a through transmission ultrasound system for medical applications. Imperium has therefore designed and constructed a proof of concept C-arm system in which the ultrasound camera and source transducer are placed on opposing ends of a C-arm mount. The patient is placed between the camera and source for imaging. As discussed in previously, this proof of concept design will serve as a foundation for the fabrication of a clinical breast imaging system. A picture of the prototype dry system is shown in Figure 16.

The C-arm system is designed to provide a means of dry-coupling a patient to an Imperium ultrasound camera in the through-transmission configuration. The system has several degrees of freedom to allow it to move into a convenient position for patient coupling. There are flexible acoustic coupling pads on the transducer and camera sides of the device to provide a comfortable, conformable interface with a variety of irregularly shaped objects. The entire C-arm is mounted to a wheeled cart for added mobility. User interface is accomplished with a standard monitor, keyboard and mouse, along with typical pulser controls.

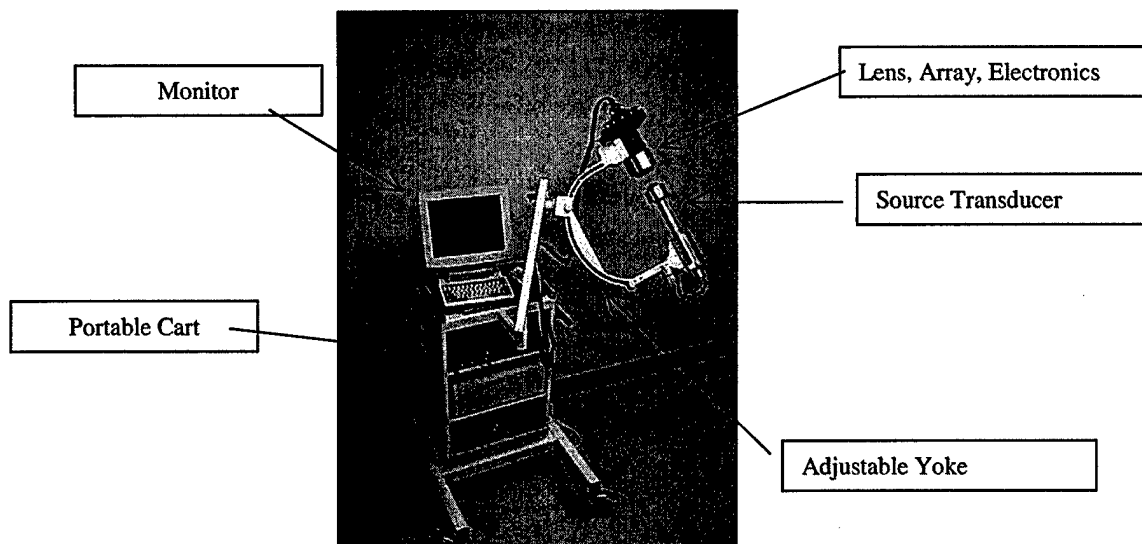


Figure 16 Proof of Concept C-arm System

Improvements in Source Pulsers and Transducers

In order to meet our unique requirements for high-amplitude, wide-area ultrasonic fields, we have designed and built our own small, low-cost, high-voltage pulsers. The pulser design generates a 100 ns pulse with an amplitude variable from 0v to 1 Kv. We will increase the voltage amplitude to 2 Kv. Because of the low impedance of the required high-frequency, large-area source transducers, driving the transducers is difficult with a single pulser driver circuit. We are investigating the use of arrays of multiple smaller transducers each driven by a separate pulser circuit.

An interesting finding is that broadband composite transducers may be detrimental to this application. The lower attenuation at lower frequencies results in loss of spatial resolution. Narrowband ceramic transducers appear to produce a sharper picture. Figures 17a and 17b show the frequency responses of a ceramic and composite transducers respectively. The peaks in Figure 17A are at 4.48 MHz and 5.78 MHz with attenuated low frequency response. The edges of the passband in Figure 17b are at 3.83 MHz and 6.96 MHz.

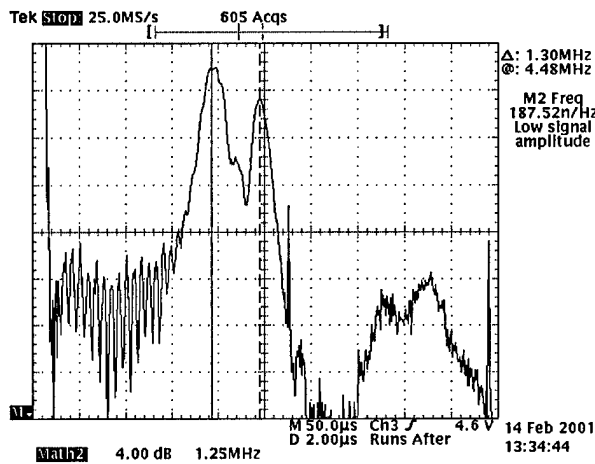


Figure 17a Narrowband Ceramic Transducer

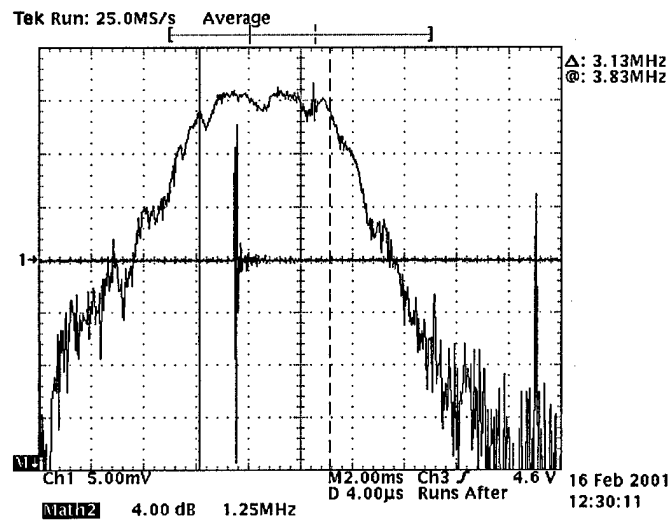


Figure 17b Broadband Composite Transducer

Simulated Breast Biopsy

To prove the feasibility of using the proposed device in image guided needle biopsy we have performed imaging with a breast phantom. The images in Figures 18a and 18b were taken by Dr. Christopher Merritt of Thomas Jefferson University. The images are of a 1 cm fatty mass with needle embedded in a gelatin phantom. In Figure 18a notice the surface reflection at the bottom of the image, the reverberations from the needle, and the presence of speckle. These are common artifacts of pulse echo ultrasound. Figure 18b which was taken with the through transmission camera from Imperium clearly shows the needle and mass.



Figure 18a Pulse Echo Ultrasound Image
Needle in gelatin phantom

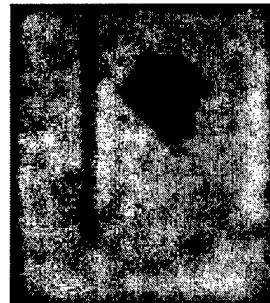


Figure 18b Transmission Ultrasound Image
Needle in phantom next to 1cm mass.

A second set of images (Figure 19) was taken with a CIRS phantom at the Georgetown University Medical Center. Figure 15 shows the sequence of needle biopsy images. The images were sampled from a sequence of 150 ultrasound images taken from 30 frames per second for five seconds. The Imperium ultrasound camera was focused on two small simulated masses and a biopsy needle about 4 cm below the surface. The needle

first punctured the target (a) and (b), then left (c), and punctured the target again (d) and (e). The needle was rotated clockwise from (e) to (f). This operation pushed the mass on the right upper corner out of the focal plane.

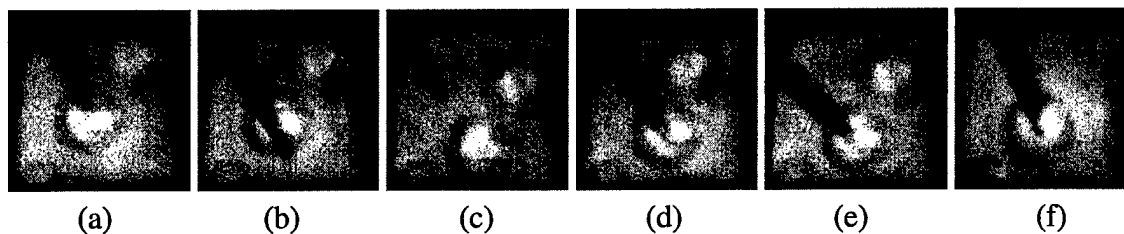


Figure 19 Needle Biopsy Sequence

In summary, we found the prototype system based on this hybrid microelectronic array that is capable of generating ultrasound images with fluoroscopy-like presentation and without speckle artifacts. The images show no obvious geometrical distortion. The resolution study indicates that a spatial resolution at ~320 microns was observable using a fan-line phantom and calcification phantom. The contrast resolution study indicates that the system is capable of differentiating objects 3mm in size with low differential contrast. The difference between the target and background materials in this experiment was as low as 0.07 dB/cm/MHz.

The potential for use in biopsy procedures is demonstrated through the imaging of breast phantoms with simulated tumors. The system is capable of imaging the area of interest in real-time. In addition, the image resolution and quality generated from the new device seem to outperform over the conventional ultrasound system in terms of inspection of mass spiculation and size of microcalcifications. Clinical investigation of the system is in-progress.

Key Research Accomplishments

We continue to improve our understanding of the parameters of this novel transmission ultrasound system and continue to work with Imperium, Inc on improvements. We will shortly begin the studies of tissues from both animals and human biopsy and mastectomy specimens. Our work was delayed by delays in obtaining approval for the use of human tissue, approval that has now been received. We have applied for and received a one-year no-cost extension to compensate for the delay in the start of this work caused by the time taken to get approval to start.

Reportable Outcomes

None to date

Other

One of our graduate students, Chu-Chuan Liu received a Pre-Doctoral Fellowship Award (# DAMD17-01-0197) from the US Army Breast Cancer Program to perform his research on the technical aspects of the Imperium Transmission Ultrasound System. He presented a poster on this at the US Army Breast Cancer Era of Hope Conference in Orlando, FL, Sept 25-28, 2002.

Conclusions

We have seen significant improvement in the design and operating characteristics of the Imperium C-Scan Transmission Ultrasound system. While delays were encountered in start-up, we now have approval to proceed, have worked with Imperium on improvements in the system, and will begin tests on tissue shortly.

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